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(71) Applicant (for all designated States except US): **TOYOTA JIDOSHA KABUSHIKI KAISHA** [JP/JP]; 1, Toyota-cho, Toyota-shi, Aichi 4718571 (JP).

(72) Inventors; and

(75) Inventors/Applicants (for US only): **OKAMURA, Masaki** [JP/JP]; c/o Toyota Jidosha Kabushiki Kaisha, 1, Toyota-cho, Toyota-shi, Aichi 4718571 (JP). **YAMASHITA, Takashi** [JP/JP]; c/o Denso Corporation, 1-1, Showa-cho, Kariya-shi, Aichi 4488661 (JP).

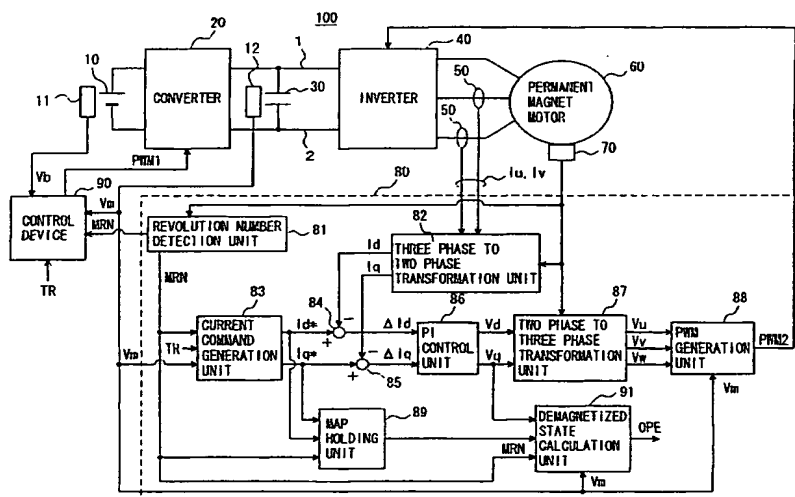
(74) Agents: **FUKAMI, Hisao** et al.; Fukami Patent Office, Mitsui Sumitomo Bank Minamimorimachi Bldg., 1-29, Minamimorimachi 2-chome, Kita-ku, Osaka-shi, Osaka 5300054 (JP).

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(54) Title: **MOTOR DRIVE APPARATUS CAPABLE OF ACCURATELY ESTIMATING DEMAGNETIZATION OF PERMANENT MAGNET MOTOR**



(57) Abstract: A map holding unit (89) holds, in the form of a map, a voltage control amount (V_{q_map}) of the q axis in a case where no demagnetization of a permanent magnet motor (60) occurs. Based on a motor revolution number, namely the number of revolutions of the motor (MRN) provided from a revolution number detection unit (81), a demagnetized state calculation unit (91) calculates a rotational angular velocity (ω). Then, based on the voltage control amount (V_{q_map}) from the map holding unit (89), a voltage control amount (V_q) to be controlled that is provided from a PI control unit (86) and the rotational angular velocity (ω), the demagnetized state calculation unit (91) calculates an amount of demagnetization (P) ($V_{q_map} - V_q$) / ω and outputs, if the amount of demagnetization is greater than a predetermined value, an operation signal (OPE) for controlling the operation of the permanent magnet motor (60).



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